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Zahirul Hoque <sup>a</sup>; Shahjahan Khan <sup>b</sup>; Jacek Wesolowski <sup>c</sup> <sup>a</sup> Department of Statistics, UAE University, Al Ain, United Arab Emirates <sup>b</sup> Department of Maths and Computing, University of Southern Queensland, Toowoomba, Queensland, Australia <sup>c</sup> Faculty of Maths and Information Science, Politechnika Warszawska, Warsaw, Poland

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# Performance of Preliminary Test Estimator Under Linex Loss Function

ZAHIRUL HOQUE,<sup>1</sup> SHAHJAHAN KHAN,<sup>2</sup> AND JACEK WESOLOWSKI<sup>3</sup>

<sup>1</sup>Department of Statistics, UAE University, Al Ain, United Arab Emirates
<sup>2</sup>Department of Maths and Computing, University of Southern Queensland, Toowoomba, Queensland, Australia
<sup>3</sup>Faculty of Maths and Information Science, Politechnika Warszawska, Warsaw, Poland

This article studies the performance of the unrestricted estimator (UE) and preliminary test estimator (PTE) of the slope parameter of simple linear regression model under linex loss function. The risk functions of both the UE and PTE are derived. The moment generating function (MGF) of the PTE is derived which turns out to be a component of the risk function. From the MGF the first two moments of the PTE are obtained and found to be identical to that obtained by using a different approach in Khan et al. (2002). The performance of the PTE is compared with that of the UE by using the analytical and graphical as well as the numerical methods. It is revealed that if the uncertain non sample prior information about the value of the slope is not too far from its true value then the PTE outperforms the UE.

**Keywords** Linex loss; Non sample prior information; Preliminary test estimator; Risk function; Unrestricted estimator.

**Mathematics Subject Classification** Primary 62G05, 62J05; Secondary 62F10, 62C15.

### 1. Introduction

The squared error loss (SEL) function is one of the most widely used loss functions in decision theory. The popularity of this symmetric loss function is due to its mathematical and interpretational convenience. Due to the symmetric nature, it fails to differentiate between overestimation and underestimation of any parameter. The criticism against the appropriateness of the SEL is ever growing since the introduction of the asymmetric linex loss (LL) by Varian (1975).

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Address correspondence to Zahirul Hoque, Department of Statistics, UAE University, P.O. Box 17555, Al Ain, UAE; E-mail: Zahirul.hoque@uaeu.ac.ae

The LL function for estimating any parameter  $\theta$  by  $\theta^*$ , is given by  $L(\delta) = b[\exp(a\delta) - a\delta - 1] \quad \forall a \neq 0, b > 0$  where  $\delta$  is the estimation error. The two parameters, a and b, in  $L(\delta)$  serve to determine the shape and scale, respectively, of  $L(\delta)$ . A positive a indicates that overestimation is more serious than underestimation and a negative a represents the reverse situation. The magnitude of a reflects the degree of asymmetry about  $\delta = 0$ . If  $a \to 0$ , then the LL reduces to the SEL. Without any loss of generality, it can be assumed that b = 1. Further details about the properties of this loss function are available in Varian (1975), Zellner (1986), Parsian and Kirmani (2002), and Parsian and Farispour (1993).

The exclusive sample information based UE of slope parameter is uniformly minimum variance unbiased estimator. The natural expectation is that the use of additional information such as non sample prior information with the sample information would result in a better estimator than UE. Based on both sample and non sample prior information, Bancroft (1944) pioneered the idea of PTE and showed that with respect to SEL function it outperforms UE under certain conditions.

The main purpose of this article is to investigate the performance of the PTE of the slope parameter of simple linear regression model under the LL function. The risk of both the UE and PTE have been derived. The MGF of the PTE is also derived in this article. The performance of the PTE relative to that of the UE is compared. It is revealed that if the non sample prior information about the value of the slope is not too far from its true value the PTE outperforms the UE. Otherwise, none of the estimators outperforms the other.

The layout of the article is as follows. The model and preliminaries are presented in Sec. 2. The risk functions of the estimators and the first two moments of the PTE are derived in Sec. 3. The performances of the estimators are investigated in Sec. 4. Finally, some concluding remarks are presented in Sec. 5.

#### 2. The Model and Preliminaries

Consider a set of *n* random sample observations  $y_i$  for i = 1, 2, ..., n from the simple linear regression model

$$y = \beta_0 + \beta_1 x + \varepsilon, \tag{1}$$

where y is the response variable,  $\beta_0$  is the intercept parameter,  $\beta_1$  is the slope parameter, x is the predictor, and  $\varepsilon$  is the error component distributed as iid  $N(0, \sigma^2)$ .

Combining sample and non sample prior information Bancroft (1944), and later Han and Bancroft (1968), developed the preliminary test estimator (PTE) for any unknown parameter. The risk properties of this estimator, under SEL, is investigated by many authors; see, for instance, Khan and Saleh (2001) and Khan et al. (2002). Giles and Giles (1993) studied the performance of the PTE of the error variance after a pre-test of exact linear restrictions on the regression coefficients in multiple regression set-up. They compared the risk of this estimator under linex loss (LL) with that under SEL. Later, Giles and Giles (1996) studied the risk of the error variance under LL after a pre-test for homoscedasticity of the variances in the two-sample heteroscedastic linear regression model.

For the linear regression model in Eq. (1), the exclusively sample information based unrestricted estimator (UE) of  $\beta_1$  is  $\tilde{\beta}_1 = S_{xx}^{-1} S_{xy}$  where  $S_{xx} = \sum_{i=1}^n (x_i - \bar{x})^2$ 

and  $S_{xy} = \sum_{i=1}^{n} (x_i - \bar{x})(y_i - \bar{y})$ . Assume that uncertain non sample prior information about the value of the slope is available either from previous study or from practical experience of researchers or experts. Such non sample prior information can be expressed in the form of the null hypothesis  $H_0: \beta_1 = \beta_{10}$  which may be true, but there is doubt. The estimator of  $\beta_1$ , under the above  $H_0$ , is known as the restricted estimator (RE), and is given by  $\hat{\beta}_{1E}^{RE} = \beta_{10}$ . A simple form of PTE of  $\beta_1$  is

$$\hat{\beta}_{1}^{\text{PTE}} = \tilde{\beta}_{1} - (\tilde{\beta}_{1} - \hat{\beta}_{1}^{\text{RE}}) I(F_{1,\nu} < F_{1,\nu}(\alpha)),$$
(2)

where I(A) is an indicator function of the set A and  $F_{1,v}(\alpha)$  is the upper  $\alpha$ -level critical value of the F statistic with 1 and v = n - 2 degrees of freedom (df) to test the null hypothesis presented earlier. Under  $H_a: \beta_1 \neq \beta_{10}$  the distribution of F is non central F with (1, v) df and non centrality parameter  $\Delta^2$  where  $\Delta = \sqrt{S_{xx}}(\beta_1 - \beta_{10})\sigma^{-1}$ .

Under the SEL, the PTE outperforms both the UE and RE in the neighborhood of  $\Delta^2 = 0$ ; see, for instance, Khan and Saleh (2001). As  $\Delta^2$  deviates further from 0, the performance of the PTE becomes worse than those of the UE and RE. However, as  $\Delta^2$  approaches a very large value the performance of the PTE becomes the same as that of the UE. On the other hand, as  $\Delta^2$  increases from zero, the performance of the RE worsen. Therefore, with respect to SEL, the PTE is regarded as an improved estimator if the value of  $\Delta^2$  is not too far from zero. However, due to the growing criticism against SEL, it is of interest to investigate the performance of the PTE under the asymmetric losses such as LL.

#### 3. The Risk of UE and PTE of the Slope

The following lemma is useful for the derivation of the risk functions of the UE and PTE.

**Lemma 3.1.** If  $Z \sim N(0, 1)$ , and Z and  $S \sim \chi_k^2$  are independent, then for any Borel measurable function  $\phi : \Re \times (0, \infty) \to \Re$  and for any  $c \in \Re$ ,

$$\operatorname{E}[\exp(cZ)\phi(Z,S)] = \exp(c^2/2)\operatorname{E}[\phi(Z+c,S)]$$
(3)

provided  $(\exp(cZ)\phi(Z, S))$  is integrable.

Proof. By definition,

$$E[\exp(cZ)\phi(Z,S)] = E[E[\exp(cZ)\phi(Z,S) | S]]$$
  
=  $E\left[\frac{1}{\sqrt{2\pi}}\int_{\Re}\phi(z,S)\exp(cz-z^2/2)dz\right]$   
=  $\exp(c^2/2)E\left[\frac{1}{\sqrt{2\pi}}\int_{\Re}\phi(z,S)\exp\left(-\frac{1}{2}(z-c)^2\right)dz\right]$ 

Consider U = Z - c. The Jacobian of the transformation is |J| = 1. Therefore,

$$\operatorname{E}[\exp(cZ)\phi(Z,S)] = \exp(c^2/2)\operatorname{E}[\phi(Z+c,S)].$$

This completes the proof of the lemma.

**Theorem 3.1.** The risk of the UE of  $\beta_1$  under the LL function is given by

 $R[\tilde{\beta}_1; \beta] = \exp(a_1^2/2) - 1$ 

where  $a_1 = a\sigma/\sqrt{S_{xx}}$ .

*Proof.* By definition, the risk function of the UE of  $\beta_1$  under the LL is

$$\mathbf{R}[\beta_1; \beta_1] = \mathbf{E}[\exp(a(\beta_1 - \beta_1))] - a \,\mathbf{E}[\beta_1 - \beta_1] - 1. \tag{4}$$

The first component of the right-hand side of (4) is

$$E[\exp(a(\hat{\beta}_1 - \beta_1))] = E[\exp(a_1 Z)]$$
(5)

where  $a_1 = a\sigma/\sqrt{S_{xx}}$  and  $Z = \sqrt{S_{xx}}(\beta_1 - \beta_{10})\sigma^{-1} \sim N(0, 1)$ . Applying Lemma 3.1 to (5) with  $\phi$  as identity, we get

$$E[\exp(a(\beta_1 - \beta_1))] = \exp(a_1^2/2).$$
 (6)

As  $\tilde{\beta}_1$  is unbiased, the second component of the right-hand side of (4) is 0. Collecting the results from (6) and substituting in (4), the expression of the risk function of the UE of  $\beta_1$  is obtained.

The following two lemmas are essential to derive the risk function of the PTE.

**Lemma 3.2.** If X follows a non central Student's t distribution with k df and non centrality parameter  $\delta$  then

$$f_{t(k,\delta)}(x) + f_{t(k,\delta)}(-x) = 2xf_{F(1,k,\delta^2)}(x^2) \quad \forall x > 0$$
(7)

where  $f_{t(k,\delta)}(\cdot)$  is the density function of a non central Student's t distribution with k df and, non centrality parameter  $\delta$ , and  $f_{F(1,k,\delta^2)}(\cdot)$  is the density function of a non central F distribution with (1, k) df and non centrality parameter  $\delta^2$ .

*Proof.* The density function of the non central Student's t distribution with k df and non centrality parameter  $\delta$  is given by

$$f_{t(k,\delta)}(x) = \frac{k^{k/2} \exp(-\delta^2/2)}{\Gamma(k/2)\sqrt{\pi}(k+x^2)^{\frac{k+1}{2}}} \sum_{i=0}^{\infty} \Gamma\left(\frac{k+1+i}{2}\right) \frac{(x\delta)^i}{i!} \left(\frac{2}{k+x^2}\right)^{i/2}.$$
 (8)

Consider now  $f_{t(k,\delta)}(x) + f_{t(k,\delta)}(-x)$  for any arbitrary x > 0. Then (8) implies that the terms of the series with odd powers of x cancel and the terms with even powers of x are duplicated. Thus,

$$f_{t(k,\delta)}(x) + f_{t(k,\delta)}(-x) = \frac{2 k^{k/2} \exp(-\delta^2/2)}{\Gamma(k/2)\sqrt{\pi}(k+x^2)^{\frac{k+1}{2}}} \sum_{i=0}^{\infty} \Gamma\left(\frac{k+1}{2}+i\right) \frac{x^{2i} \delta^{2i}}{(2i)!} \left(\frac{2}{k+x^2}\right)^i$$

$$= \frac{2k^{k/2}\exp(-\delta^2/2)}{\Gamma(k/2)\sqrt{\pi}(k+x^2)^{\frac{k+1}{2}}} \sum_{i=0}^{\infty} \Gamma\left(\frac{k+1}{2}+i\right) \frac{(x^2)^i (\delta^2)^i}{2^i i! (2i-1)!!} \frac{2^i}{(k+x^2)^i}$$
$$= 2x \frac{k^{k/2}\exp(-\delta^2/2)(x^2)^{-1/2}}{\Gamma(k/2)(k+x^2)^{\frac{k+1}{2}}} \sum_{i=0}^{\infty} \frac{\Gamma\left(\frac{k+1}{2}+i\right)}{i! \Gamma\left(\frac{1}{2}+i\right)} \left\{\frac{x^2 \delta^2}{2(k+x^2)}\right\}^i = 2x f_{F(1,k,\delta^2)}(x^2).$$

This completes the proof of the lemma.

Lemma 3.3. For any two positive integers m and n,

$$\frac{\partial f_{F(m,n,D)}(x)}{\partial D} = -\frac{1}{2} f_{F(m,n,D)}(x) + \frac{m}{2(m+2)} f_{F(m+2,n,D)}\left(\frac{mx}{m+2}\right), \quad x, D \in [0,\infty)$$

where  $f_{F(l,n,D)}(\cdot)$  denotes the density function of a non central F distribution with (l, n) df and non centrality parameter D.

*Proof.* The density function of the non central F with (m, n) df and non centrality parameter D is given by

$$f_{F(m,n,D)}(x) = \frac{\exp(-D/2)m^{m/2}n^{n/2}}{\Gamma(n/2)} \frac{x^{\frac{m}{2}-1}}{(n+mx)^{\frac{m+n}{2}}} \sum_{j=0}^{\infty} \left[\frac{mxD}{2(n+mx)}\right]^{j} \frac{\Gamma\left(\frac{m+n}{2}+j\right)}{\Gamma\left(\frac{m}{2}+j\right)j!}.$$

Derivative of this density function leads to the above-mentioned result.

**Theorem 3.2.** The risk function of the preliminary test estimator of the slope parameter  $\beta_1$  under the LL function is given by

$$R[\tilde{\beta}_{1}^{\text{PTE}};\beta_{1}] = \exp(-a_{1}\Delta)G_{1,\nu}(c;\Delta^{2}) + \exp(a_{1}^{2}/2)[1 - G_{1,\nu}(c;(\Delta + a_{1})^{2})] + a_{1}\Delta G_{3,\nu}(c/3;\Delta^{2}) - 1,$$
(9)

where  $c = F_{1,v}(\alpha)$  and  $G_{a,v}(q; \theta)$  is the cdf of non central F distribution with (a, v) df, non centrality parameter  $\theta$  and evaluated at q.

*Proof.* By definition, the risk function of the PTE of  $\beta_1$  under the LL function is

$$\mathbf{R}[\hat{\beta}_1^{\text{PTE}};\beta_1] = \mathbf{E}[\exp(a\Phi)] - a\mathbf{E}[\Phi] - 1 \tag{10}$$

where  $\Phi = \hat{\beta}_1^{\text{PTE}} - \beta_1$ .

The first component of the right-hand side of (10) is

$$E[\exp(a\Phi)] = E[\exp(a\{(\tilde{\beta}_{1} - \beta_{1}) - (\tilde{\beta}_{1} - \beta_{10})I(F_{1,\nu} < F_{1,\nu}(\alpha))\})] \\ \times [I(F_{1,\nu} < F_{1,\nu}(\alpha)) + I(F_{1,\nu} \ge F_{1,\nu}(\alpha))] \\ = \exp(a(\beta_{10} - \beta_{1}))P(F_{1,\nu} < c) + E[\exp(a(\tilde{\beta}_{1} - \beta_{1}))I(F_{1,\nu} \ge c)]$$
(11)

where  $c = F_{1,\nu}(\alpha)$ .

The first component of the right-hand side of (11) is

$$\exp(a(\beta_{10} - \beta_1))P(F_{1,\nu} < c) = \exp(-a_1 \Delta)G_{1,\nu}(c; \Delta^2).$$
(12)

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The second component of the right-hand side of (11) can be written as

$$\operatorname{E}[\exp(a(\tilde{\beta}_{1}-\beta_{1}))I(F_{1,\nu}\geq c)] = \operatorname{E}\left[\exp(a_{1}Z)I\left(\frac{(Z+\Delta)^{2}}{\nu S_{n}^{2}/\sigma^{2}}\geq c\right)\right],$$
(13)

where  $a_1 = \frac{a\sigma}{\sqrt{S_{xx}}}$ ,  $Z \sim N(0, 1)$  and  $(vS_n^2/\sigma^2) \sim \chi_v^2$ . Z and  $S_n$  are independent. Applying Lemma 3.1 to (13) with  $\phi(X, Y) = I(\frac{(X+\Delta)^2}{Y} \ge c)$ , we get

$$\mathbf{E}[\exp(a(\tilde{\beta}_1 - \beta_1))I(F_{1,\nu} \ge c)] = \exp(a_1^2/2)[1 - G_{1,\nu}(c; (\Delta + a_1)^2)].$$
(14)

Combining (12) and (14), the first component of the right-hand side of (10) yields

$$E[\exp(a\Phi)] = \exp(-a_1\Delta)G_{1,\nu}(c;\Delta^2) + \exp(a_1^2/2)[1 - G_{1,\nu}(c;(\Delta + a_1)^2)].$$
 (15)

From (15) the moment generating function of the PTE of  $\beta_1$  is

$$m(a) = \exp(-a_1 \Delta) \left[ \int_{-c}^{0} f_{t(\nu,\Delta)}(x) dx + \int_{0}^{c} f_{t(\nu,\Delta)}(x) dx \right] + \exp(a_1^2/2) \left[ 1 - \int_{-c}^{0} f_{t(\nu,\Delta-a_1)}(x) dx - \int_{0}^{c} f_{t(\nu,\Delta-a_1)}(x) dx \right].$$
(16)

Writing  $g_{t(v,\Delta)}(x) = f_{t(v,\Delta)}(x) + f_{t(v,\Delta)}(-x)$  for any x > 0 in (16) we get

$$m(a) = \exp(-a_1 \Delta) \int_0^c g_{t(\nu,\Delta)}(x) dx + \exp(a_1^2/2) \int_c^\infty g_{t(\nu,\Delta-a_1)}(x) dx.$$
(17)

Applying Lemma 3.2 in (17) we get

$$m(a) = \exp(-a_1\Delta) \int_0^c f_{F(1,\nu,\Delta^2)}(y) dy + \exp(a_1^2/2) \int_c^\infty f_{F(1,\nu,(-\Delta-a_1)^2)}(y) dy.$$

Differentiating both sides of the above equation with respect to a, then using Lemma 3.3 and finally changing the variable y/3 to t in the left integral we get

$$m'(a) = \frac{\sigma}{\sqrt{S_{xx}}} \bigg[ -\Delta \exp(-a_1 \Delta) \int_0^c f_{F(1,\nu,\Delta^2)}(y) dy + a_1 \exp(a_1^2/2) \\ \times \int_c^\infty f_{F(1,\nu,(\Delta+a_1)^2)}(y) dy - (\Delta+a_1) \exp(a_1^2/2) \int_c^\infty f_{F(1,\nu,(\Delta+a_1)^2)}(y) dy \\ + (\Delta+a_1) \exp(a_1^2/2) \int_{c/3}^\infty f_{F(3,\nu,(\Delta+a_1)^2)}(y) dy \bigg].$$
(18)

Putting a = 0 in (18) we get  $E(\Phi) = -(\beta_1 - \beta_{10})G_{3,\nu}(c/3; \Delta^2)$  which is the bias function or equivalently the first moments of the PTE of  $\beta_1$ . Therefore, the second component of the right-hand side of (10) is

$$aE[\Phi] = -a_1 \Delta G_{3,\nu}(c/3; \Delta^2).$$
(19)

Collecting the expressions from (15) and (19) and plugging into (10), the risk function of the PTE of  $\beta_1$  under the LL function is obtained. This completes the proof of the theorem.

Differentiating both sides of (18) with respect to *a*, then using Lemma 3.3 and finally putting a = 0, the mse function of the PTE of  $\beta_1$  is obtained as

$$\mathbf{M}[\hat{\beta}_{1}^{\text{PTE}};\beta_{1}] = S_{xx}^{-1}\sigma^{2}[1 - G_{3,v}(c/3;\Delta^{2}) + \Delta^{2}\{2G_{3,v}(c/3;\Delta^{2}) - G_{5,v}(c/5;\Delta^{2})\}].$$

For an equivalent expression of the mse function of the shrinkage preliminary test estimator of  $\beta_1$  readers may see Khan et al. (2002). Similarly, putting a = 0 in the *m*th order derivative of (16) the *m*th moment of the PTE can be obtained.

#### 4. Performance Analysis

For any non zero value of  $\Delta$ , the risk function of the PTE of  $\beta_1$  can be written as

$$\mathbf{R}\left[\hat{\beta}_{1}^{\text{PTE}};\beta_{1}\right] = \mathbf{R}\left[\tilde{\beta}_{1};\beta_{1}\right] + g(\Delta), \tag{20}$$

where  $g(\Delta) = \exp(-a_1\Delta)G_{1,\nu}(c; \Delta^2) + a_1\Delta G_{3,\nu}(c/3; \Delta^2) - \exp(a_1^2/2)G_{1,\nu}(c; (\Delta + a_1)^2)$ . Therefore, the efficiency of the PTE relative to the UE can be written as

$$\operatorname{Eff}[\hat{\beta}_{1}^{\operatorname{PTE}}; \tilde{\beta}_{1}] = \left[\exp(a_{1}^{2}/2) - 1\right] \left[\exp(a_{1}^{2}/2) - 1 + g(\Delta)\right]^{-1}.$$
 (21)

Under the null hypothesis,  $\Delta = 0$  and hence

$$g(\Delta) = G_{1,\nu}(c;0) - \exp(a_1^2/2)G_{1,\nu}(c;a_1^2) < 0 \quad \forall a \neq 0.$$
<sup>(22)</sup>

Therefore, at  $\Delta = 0$  the PTE is more efficient than the UE.

For any positive *a*, if  $\Delta$  is positive  $a_1 \Delta G_{3,\nu}(c/3; \Delta^2)$  is also positive. Therefore, for positive *a* as  $\Delta$  grows larger from 0 efficiency of PTE decreases and crosses the 1line at  $\Delta = (\exp(a_1^2/2)G_{1,\nu}(c; (\Delta + a_1)^2) - \exp(-a_1\Delta)G_{1,\nu}(c; \Delta^2))/(a_1G_{3,\nu}(c/3; \Delta^2))$  regardless of the value of *a*.

For any negative *a*, if  $\Delta$  is positive  $a_1 \Delta G_{3,\nu}(c/3; \Delta^2)$  is negative. Therefore, for negative *a*, as  $\Delta$  grows larger from 0, the efficiency of PTE grows larger, reaching its maximum at some  $\Delta$  depending on the magnitude of *a*, and then starts decreasing and crosses the 1-line for the value of  $\Delta$  given above regardless of the value of *a*. As  $\Delta \rightarrow \infty$ ,  $g(\Delta)$  tends to 0, and hence, Eff $[\hat{\beta}_1^{\text{PTE}}; \tilde{\beta}_1] \rightarrow 1$ . Therefore, starting from a certain large  $\Delta$ , the efficiency of PTE is no different from that of UE.

For very small values of *a*, the growth pattern of the efficiency of the PTE for both positive and negative values of  $\Delta$  are very similar. Because for very small values of *a*, the LL function reduces to the SEL function. From the foregoing analyses and Fig. 1 it is clear that the efficiency of the PTE relative to the UE depend on the three factors, the values of  $\alpha$ ,  $\Delta$ , and *a*. The value of *a* is determined by the experimenter according to the potential impact of the positive and negative errors of estimation, and the value of  $\Delta$  is usually unknown to the experimenter. Regardless of the values of *a* and  $\Delta$ , the efficiency of the PTE is a function of  $\alpha$ . The question is which value of  $\alpha$  should be used for the preliminary test?



Figure 1. Efficiency of PTE relative to UE for  $\alpha = 0.2$ , n = 25, and selected a.

Let us consider the efficiency function of the PTE of  $\beta_1$  relative to the UE as a function of  $\alpha$  and  $\Delta$ . Therefore,

Eff
$$[\hat{\beta}_1^{\text{PTE}}; \alpha, \Delta] = [\exp(a_1^2/2) - 1] [\exp(a_1^2/2) - 1 + g(\Delta)]^{-1}.$$
 (23)

From the analyses of the relative efficiency function of the PTE it is evident that the PTE does not have uniform domination over the UE for all values of  $\Delta$ .

Also, the value of  $\Delta$  is usually unknown to the experimenter. Thus, we preassign a value of the relative efficiency, say Eff<sub>o</sub>, that we are willing to accept. Consider the set  $A_{\alpha} = (\alpha \mid \text{Eff}\{\hat{\beta}_1^{\text{PTE}}; \alpha, \Delta\} \ge \text{Eff}_o)$  for all  $\Delta$ . An estimator  $\hat{\beta}_1^{\text{PTE}}$  is chosen which maximizes  $\text{Eff}[\hat{\beta}_1^{\text{PTE}}; \alpha, \Delta] \forall \alpha \in A_{\alpha}$  and  $\Delta$ . Thus, we solve

$$\max_{\alpha} \min_{\Delta} \operatorname{Eff}[\hat{\beta}_{1}^{\text{PTE}}; \alpha, \Delta] = \operatorname{Eff}_{o}$$
(24)

for  $\alpha$ . The solution provides the maximum and minimum guaranteed efficiencies of the PTE of  $\beta_1$  relative to the UE, for any selected values of *n* and  $\Delta$ . Table 1 presents the maximum guaranteed efficiency (Eff<sup>\*</sup>) and minimum guaranteed efficiency (Eff<sub>0</sub>) of the PTE of  $\beta_1$  relative to the UE, and the value of  $\Delta$  ( $\Delta_o$ ) at which Eff<sub>0</sub> occurs, for selected values of *a*, *n*, and  $\alpha$ . For example, if *a* = 3 and *n* = 20, and the experimenter wishes to achieve the minimum guaranteed efficiency 0.6055 of the PTE of  $\beta_1$ , the recommended value of  $\alpha$  is 0.20. This minimum guaranteed efficiency

		Sample size, n						
α		10	15	20	25	30	35	40
0.05	Eff*	4.2674	3.9892	3.8713	3.80640	3.7653	3.7369	3.7162
	$\operatorname{Eff}_{o}$	0.2661	0.3076	0.3279	0.3279	0.3401	0.3401	0.3545
	$\Delta_o$	-2.6300	-2.4700	-2.3850	-2.3950	-2.3550	-0.3250	-2.3004
0.10	$Eff^*$	2.5615	2.4468	2.3978	2.3706	2.3534	2.3415	2.3328
	$\operatorname{Eff}_{o}$	0.3807	0.4202	0.4393	0.4507	0.4585	0.4641	0.4684
	$\Delta_o$	-2.3550	-2.2255	-2.1515	-2.1448	-2.1050	-2.1105	-2.0850
0.15	Eff*	1.9556	1.8907	1.8629	1.8474	1.8376	1.8308	1.8258
	Eff <sub>o</sub>	0.4748	0.5112	0.5285	0.5390	0.5462	0.5511	0.5550
	$\Delta_o$	-2.1750	-2.0850	-2.0390	-2.0100	-2.0055	-2.0025	-1.9750
0.20	$Eff^*$	1.6429	1.6014	1.5835	1.5736	1.5673	1.5629	1.5597
	$Eff_o$	0.5573	0.5900	0.6055	0.6148	0.6211	0.6256	0.6291
	$\Delta_o$	-2.0610	-1.9800	-1.9500	-1.9302	-1.9100	-1.9000	-1.8950
0.25	$Eff^*$	1.4530	1.4247	1.4125	1.4057	1.4014	1.3984	1.3962
	$\operatorname{Eff}_{o}$	0.6310	0.6597	0.6733	0.6814	0.6868	0.6908	0.6938
	$\Delta_o$	-1.9850	-1.9250	-1.8950	-1.8755	-1.8609	-1.8550	-1.8500
0.30	Eff*	1.3268	1.3068	1.2982	1.2934	1.2904	1.2883	1.2867
	$Eff_o$	0.6969	0.7215	0.7331	0.7400	0.7446	0.7480	0.7506
	$\Delta_o$	-1.925	-1.8650	-1.8459	-1.8255	-1.8100	-1.8080	-1.7968

Table 1Maximum and minimum efficiencies of PTE relative to UE for a = 3

attains at  $\Delta_o = -1.95$ . For a = -3, the same minimum guaranteed efficiency occurs at  $\Delta_o = 1.95$ . In general, if *a* is negative the value of  $\Delta_o$  is positive and vice versa.

### 5. Concluding Remarks

This article has introduced the computation of any order derivative of the non central F distribution with respect to the non centrality parameter and the derivation of the MGF of the PTE. Moment of the PTE of any order can be obtained from this MGF. For illustration, the bias and mse functions are derived. It is revealed that if the non sample prior information regarding the value of the parameter is not too far from its true value the PTE outperforms the UE. This result reaffirms the superiority of the PTE under the SEL function. Similar to the shape of the LL function the shape of the risk function of the PTE is also asymmetric. As the value of the shape parameter of the loss function grows smaller, the shape of the risk function of the PTE approaches symmetry.

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