

A MEMETIC APPROACH FOR SEQUENTIAL SECURITY GAMES ON A PLANE WITH MOVING TARGETS

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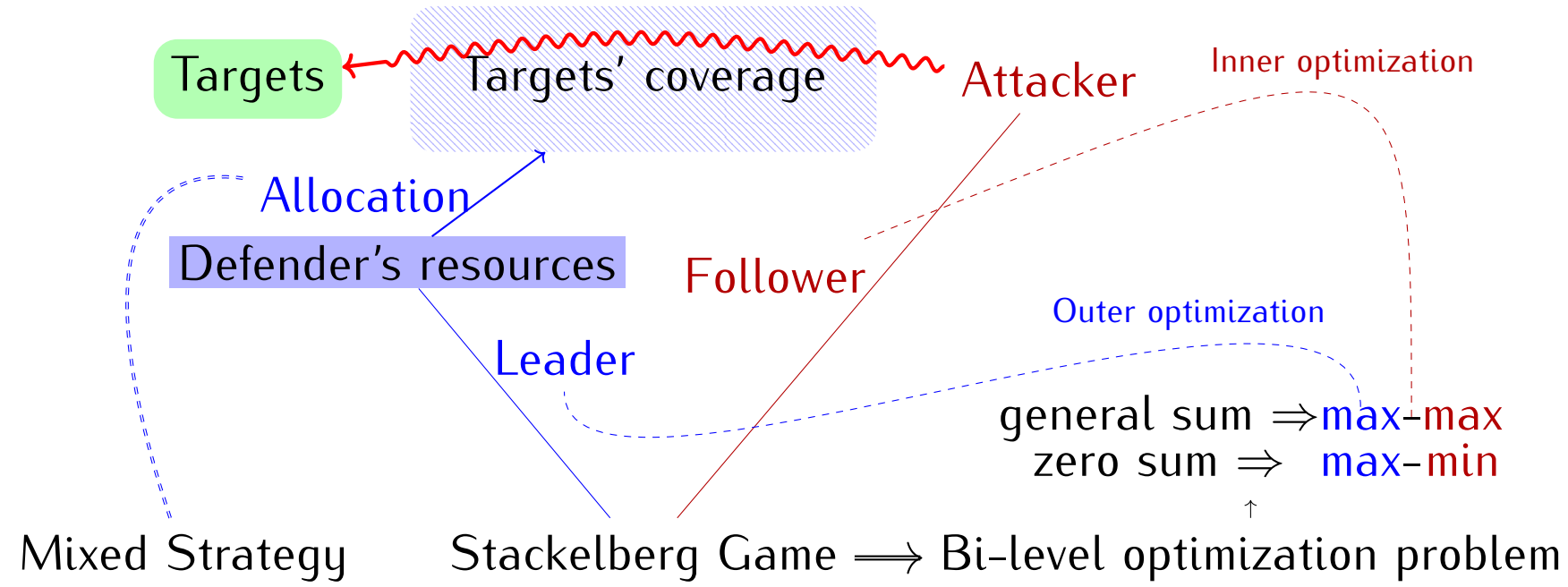
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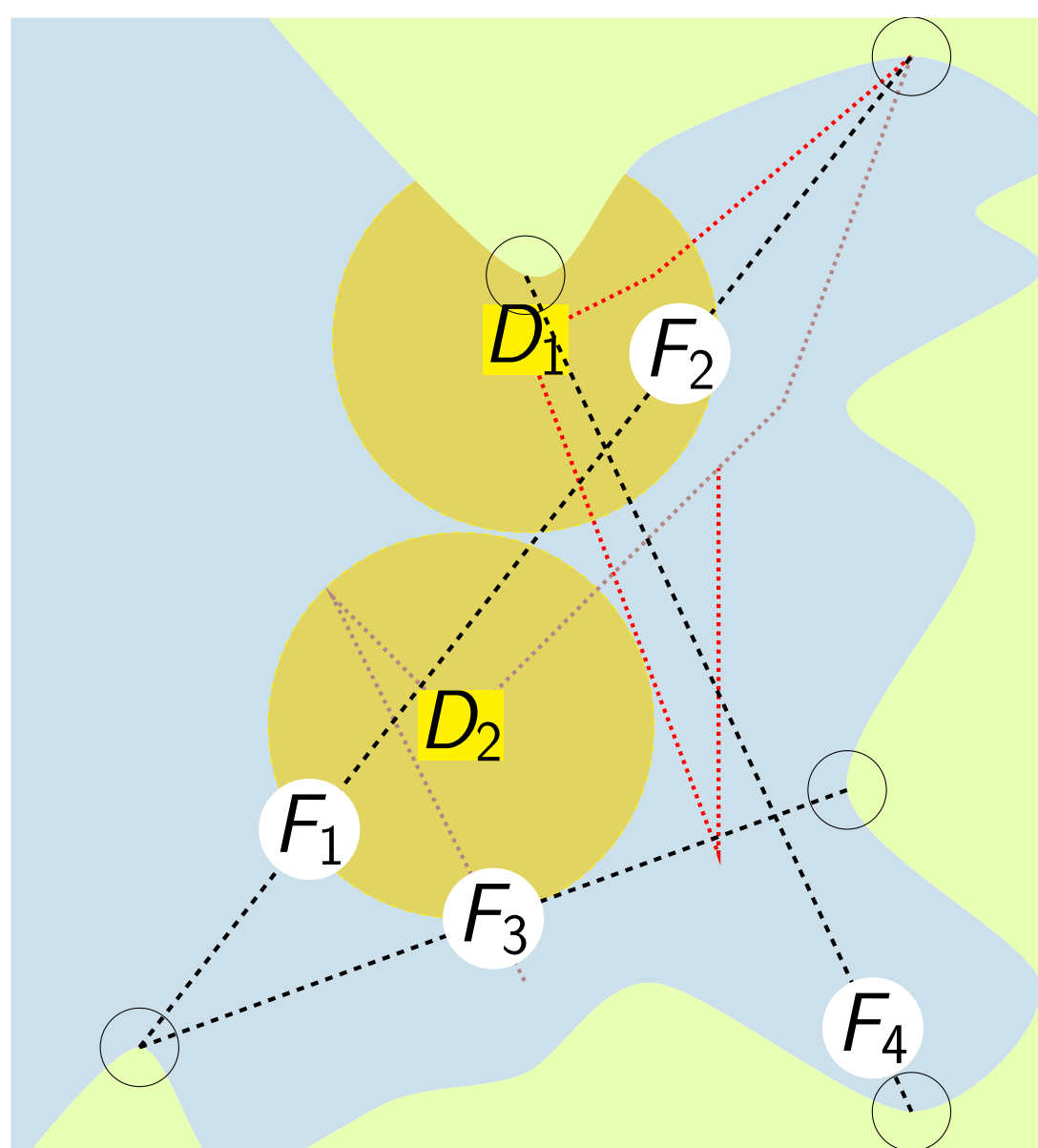
Thirty-Third AAAI Conference on Artificial Intelligence, January 27 — February 1, 2019, Honolulu, Hawaii, USA

★ Multi-Act Game • Good scalability • Repeatability • Anytime method ★

Security Games



Game (with moving targets)



Time: game lasts several rounds

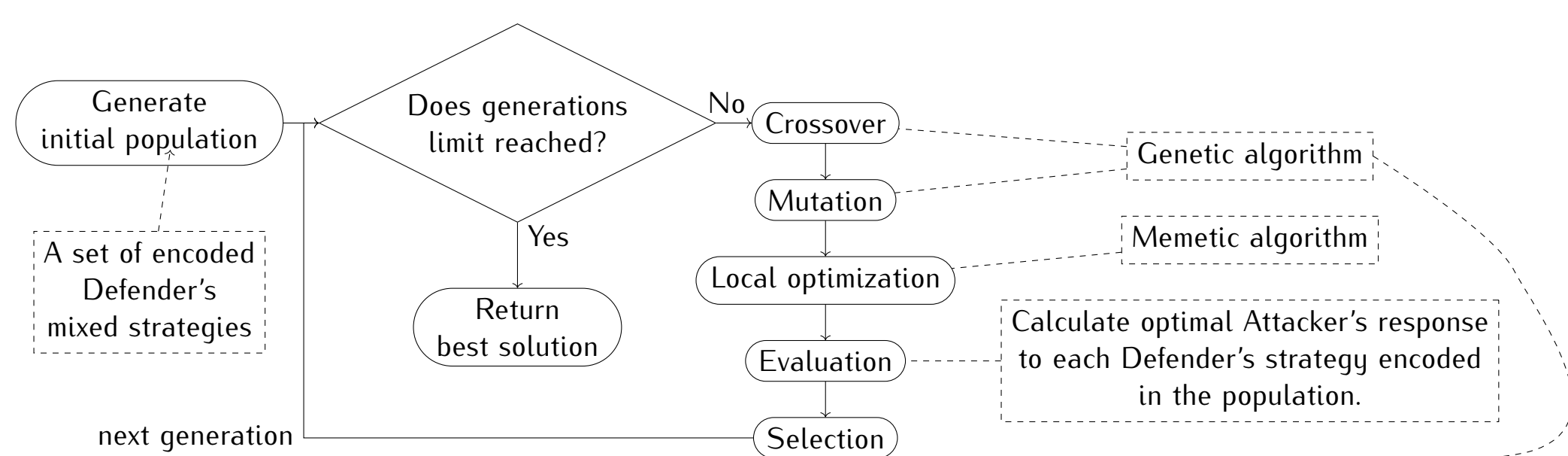
Ports: fixed locations

Ferries: single route, fixed schedule

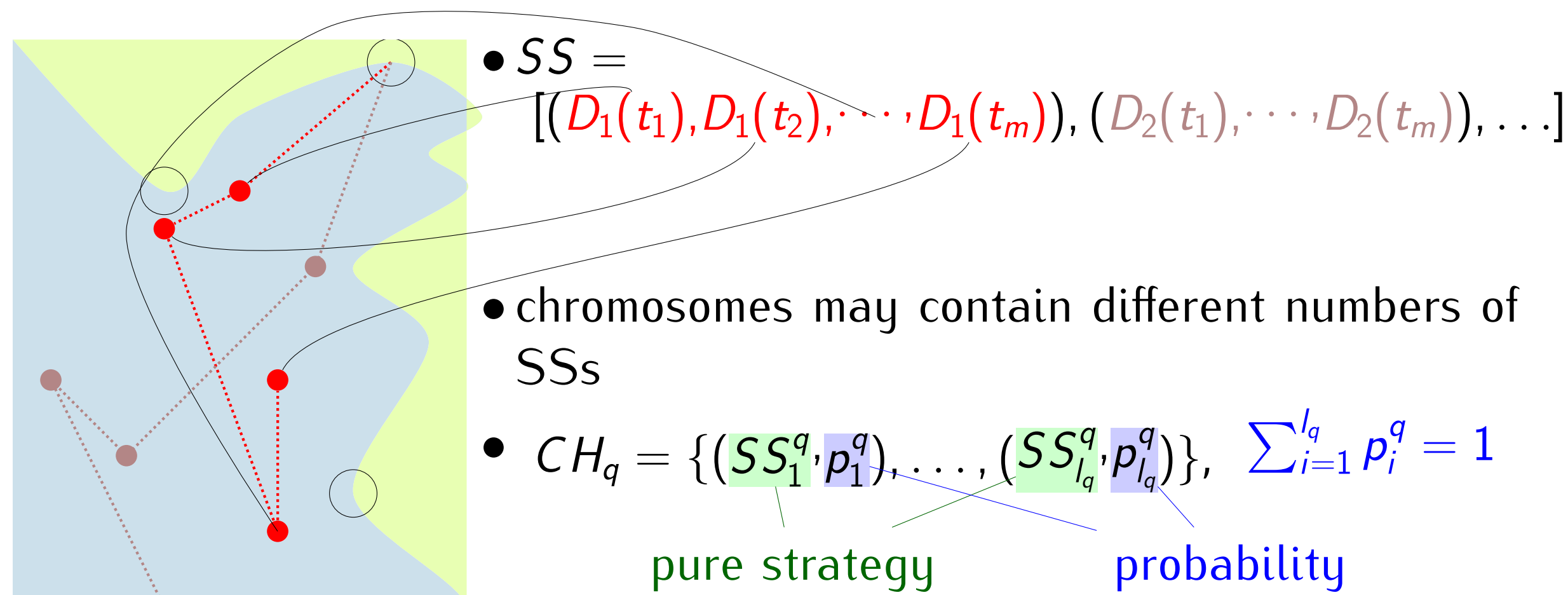
Defenders: protect radial area around them

Attacker: tries to attack a ferry, attack lasts several rounds

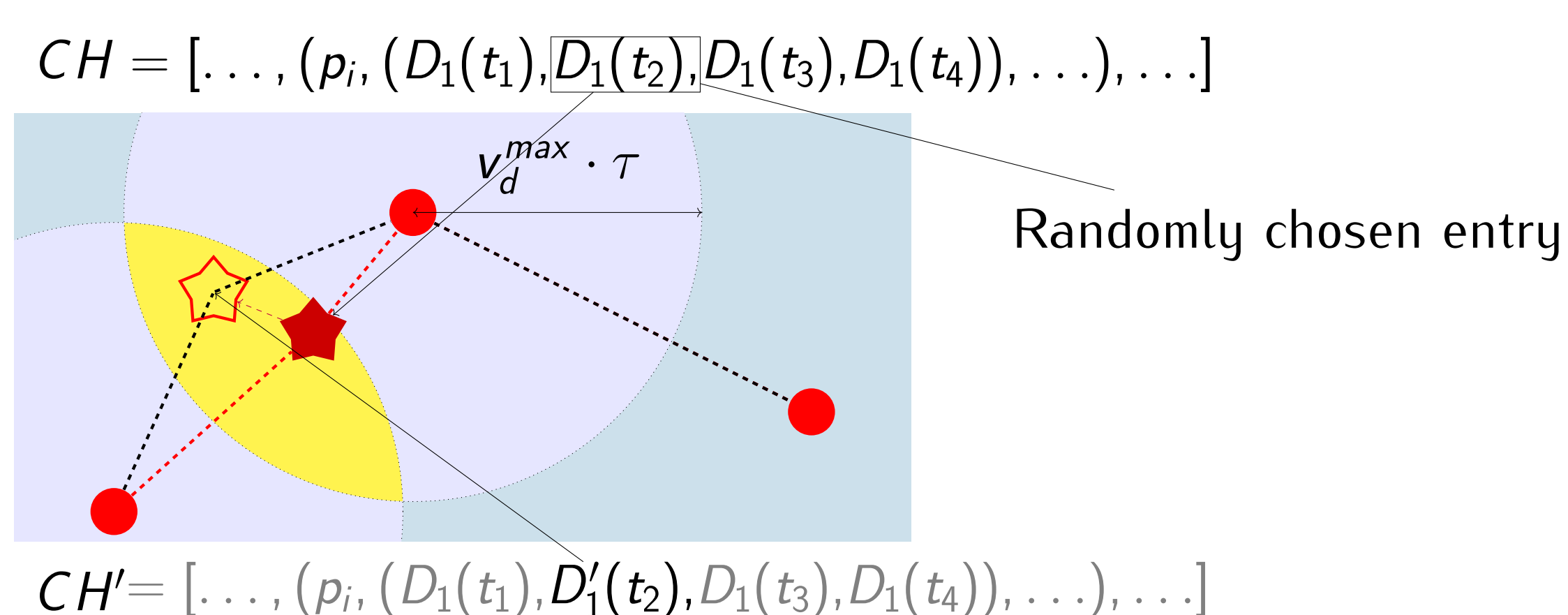
Memetic algorithm



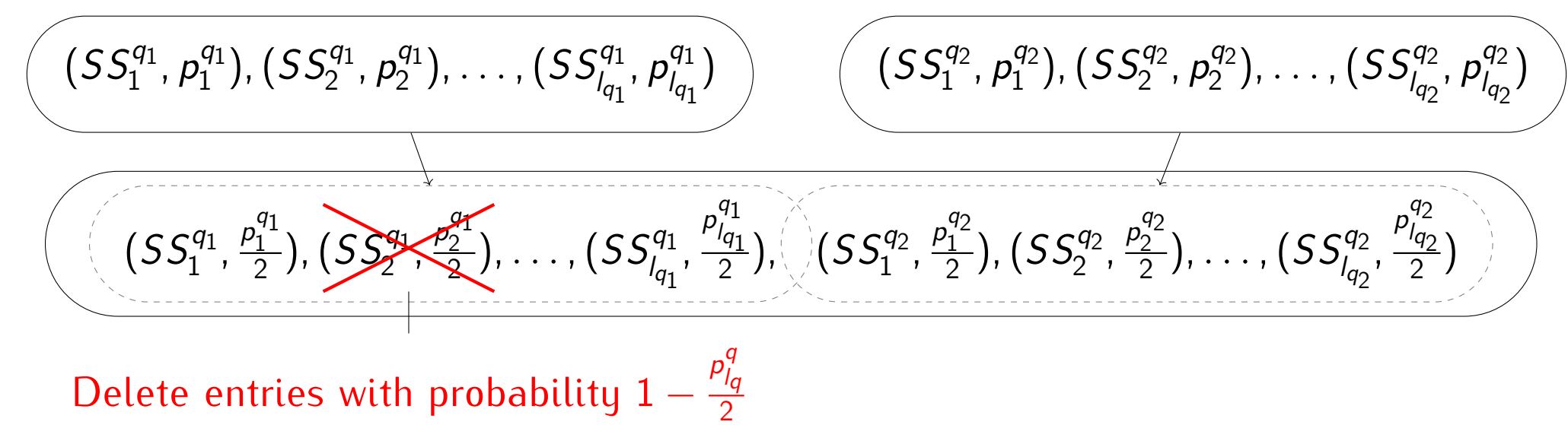
Chromosome (Defender's strategy encoding)



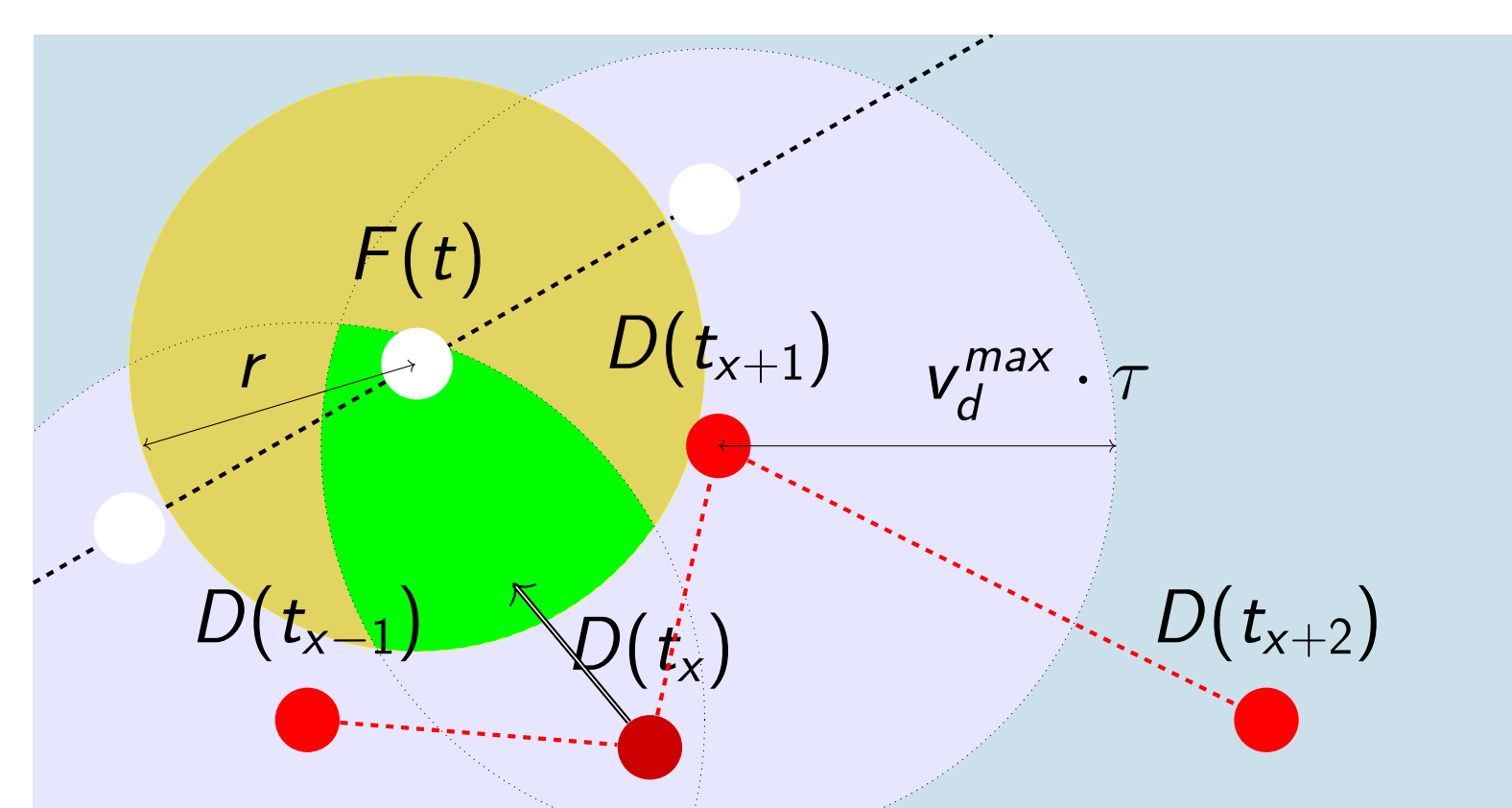
Mutation



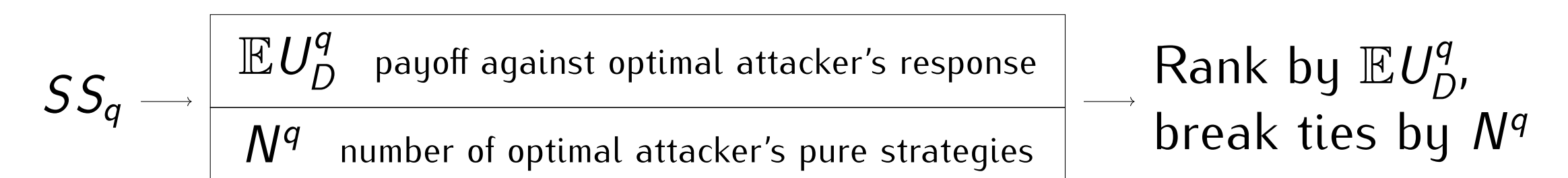
Crossover



Local optimization



Evaluation



Experiments

6150 random games

Results baseline: SMOS-based program

MA Parameters:

parameter	value
population size	2000
# generations	2000
mutation rate	0.2
mutation repeats	10
crossover rate	0.9
selection pressure	0.9
# elite chromosomes	2

$$\max \sum_{i \in \mathcal{I}} U^d(i, f)$$

$$0 \leq a - \sum_{g \in \mathcal{G}} U^d(g, f) \leq (1 - q_r) \cdot M$$

$$\sum_{i \in \mathcal{I}} q_r = 1$$

$$c(i, t_k, f) = \sum_{j \in \mathcal{M}(i)} f_{(i, t_k), (j, t_k), f}$$

$$\forall i \in \mathcal{Z}, k \in \{0, \dots, \tau - 1\}, f \in \mathcal{F}$$

$$c(i, t_k, f) = \sum_{j \in \mathcal{M}(i)} f_{(i, t_k), (j, t_k), f}$$

$$\forall i \in \mathcal{Z}, k \in \{1, \dots, \tau\}, f \in \mathcal{F}$$

$$q_r \cdot m = \sum_{i \in \mathcal{Z}} c(i, t_k, f) \quad k \in \{0, \tau\}$$

$$q_r \cdot DS(i) = c(i, 0, f) \quad \forall i \in \mathcal{S}, f \in \mathcal{F}$$

$$1 - m_1(g, f) M_2 \leq dpp(g, f) \leq 1$$

$$\sum_{(i, t) \in \mathcal{M}(f)} c(i, t, g) - m_2(g, f) M_2 \leq dpp(g, f) \leq \sum_{(i, t) \in \mathcal{M}(f)} c(i, t, g)$$

$$m_1(g, f) + m_2(g, f) = 1, \quad \forall f, g \in \mathcal{F}$$

$$q_r - m_2(g, f) M_2 \leq dpp_{neg}(g, f) \leq q_r$$

$$1 - dpp(g, f) - m_2(g, f) M_2 \leq dpp_{neg}(g, f) \leq 1 - dpp(g, f)$$

$$m_2(g, f) + m_3(g, f) = 1, \quad \forall f, g \in \mathcal{F}$$

$$\forall i, g, f, m_1(g, f) \in \{0, 1\} \quad \forall f, g \in \{0, 1\}$$

$$f_{(i, t_k), (j, t_k), f} \in \mathbb{R}, dpp(g, f) \in \mathbb{R}$$

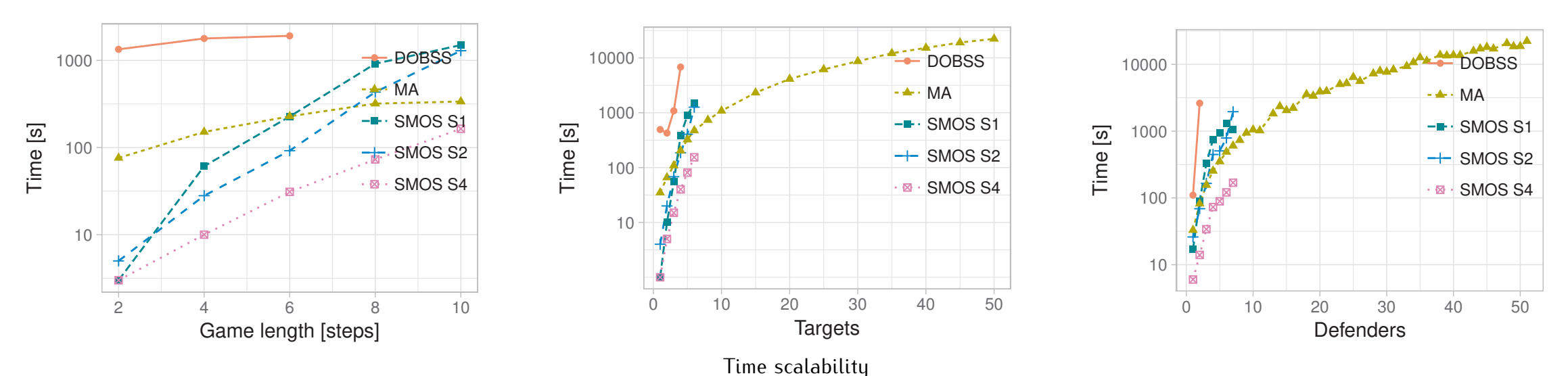
$$c(i, t_k, f) \in \mathbb{R} \quad \forall g, f, dpp_{neg}(g, f) \in \mathbb{R}$$

$$U^d(g, f) = dpp_{neg}(g, f) U^{d^+}(f) + dpp(g, f) U^{d^-}(f)$$

$$U^d(g, f) = dpp_{neg}(g, f) U^{d^+}(f) + dpp(g, f) U^{d^-}(f)$$

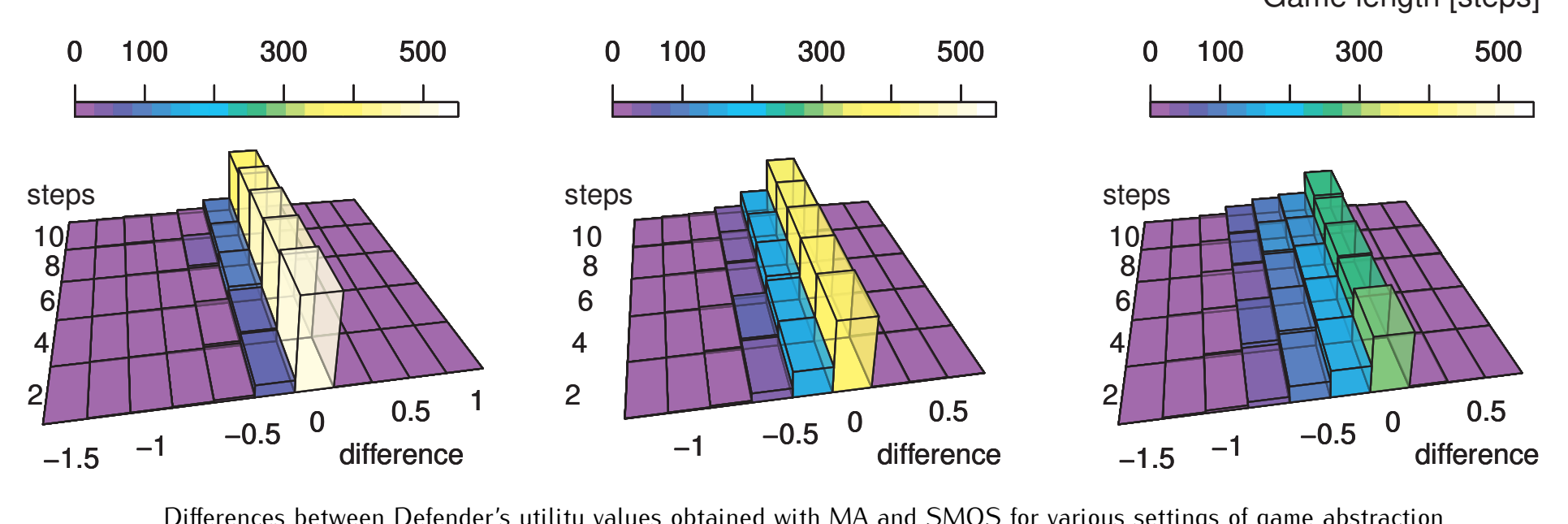
Xinrun Wang et al. "Catching Captain Jack: Efficient time and space dependent patrols to combat oil-siphoning in international waters". In: AAAI Conference on Artificial Intelligence. 2018, pp. 208-215

Results



Close to linear scalability

Large instances:



Differences between Defender's utility values obtained with MA and SMOS for various settings of game abstraction